

#### Lista publikacji PŁ

1. Zubrycki I., Granosik G. Test setup for multi-finger gripper control based on robot operating system (ROS), Proc. of 9th Int. Workshop on Robot Motion and Control, pp. 135-140, July 3-5, 2013, Wałowo, Poland, 2013
2. Zubrycki I., Granosik G. Grip recognition and control of 3-finger gripper with sensor glove, to be published in Proc. of Int. Conference on Robotics and Artificial Intelligence. Problems and perspective. (RAIPAP'13), Brest, Belarus, 4-6 November 2013
3. Zubrycki I., Granosik G. Introducing modern robotics with ROS and Arduino, including case studies, Journal of Automation, Mobile Robotics & Intelligent Systems JAMRIS, vol. 8, no. 1, pp. 69-75, DOI: 10.14313/JAMRIS\_1-2014/9, pISSN 1897-8649
4. Zubrycki I., Granosik G. Using integrated vision systems: Three Gears and Leap Motion, to control a 3-finger dexterous gripper, accepted to Automation 2014